

PHYSICS 489/1489

LECTURE 11: SYMMETRIES

ANNOUNCEMENTS

- Problem set 2 due next Tuesday at 1700
 - Box K
- Office hours tomorrow:
 - Might be a bit late . . . hopefully back in the office by 1415.

E&M WITH CHARGED DIRAC PARTICLES

$$H_0 = \gamma^0 (\vec{\gamma} \cdot \mathbf{p} + m) \quad V = q \gamma^0 \gamma^\mu A_\mu \quad A^\mu = (\phi, \mathbf{A})$$

- Can be derived from "minimal substitution"

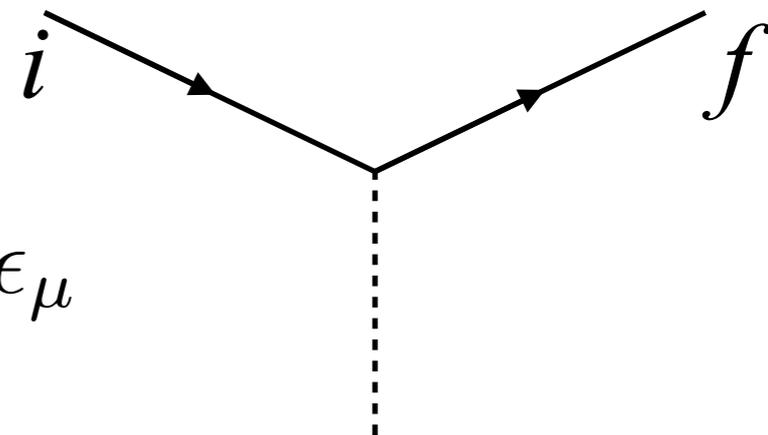
$$\partial_\mu \Rightarrow \partial_\mu + iqA_\mu \quad p_\mu \Rightarrow p_\mu - qA_\mu$$

- we'll see later that this can arise from "gauge invariance"
- for now, you can see:

$$E \Rightarrow E - q\phi \quad \mathbf{p} \Rightarrow \mathbf{p} - q\mathbf{A}$$

- i.e. impact from scalar/vector potential on the energy of the particle
- We can then express the interaction as follows

$$\langle \psi_f | V | \psi_i \rangle \Rightarrow u_f^\dagger Q \gamma^0 \gamma^\mu \epsilon_i u_i \Rightarrow Q \bar{u}_f \gamma^\mu u_i \epsilon_\mu$$



from QED lecture

SYMMETRY

- An operation on something that leaves it unchanged
- Mathematically, symmetries form "groups"
 - closure: one operation followed by another is another symmetry operation
 - identity: doing nothing is a symmetry operation
 - inverse: for each operation, there is another symmetry operation that undoes it.
 - associativity: $O_1(O_2O_3) = (O_1O_2)O_3$
- Noether's theorem:
 - symmetry in a system \leftrightarrow conservation law



NOETHER'S THEOREM IN QM

- We can express a symmetry operation on a state as an operator:

$$|\psi\rangle \rightarrow U|\psi\rangle \quad |U\psi\rangle \equiv U|\psi\rangle$$

- in order for the physical predictions to be unchanged by the operation, it must preserve:

- normalization $\langle\psi|\psi\rangle \rightarrow \langle U\psi|U\psi\rangle$

$$\langle U\psi|U\psi\rangle \rightarrow \langle\psi|U^\dagger U\psi\rangle$$

- can see that U must be unitary, i.e. $U^\dagger U = 1$
- eigenvalues of operators
 - particularly the Hamiltonian $[H, U] = 0$

CONTINUOUS GROUPS

- A continuous group is one that can be parameterized by continuous parameter(s):

$$U \rightarrow U(\theta)$$

- Examples:
 - rotations ("special" orthogonal matrices)
 - e.g. matrices where $O^T O = O O^T = 1$
 - with determinant 1
 - "SO(N)": special orthogonal matrices of dimension N
 - "special unitary" matrices:
 - unitary matrices with determinant 1
 - "SU(N)": special unitary matrices of dimension N

GENERATORS

- For a continuous group, we can consider an infinitesimal transformation (in a Taylor expansion sense)

$$U(\epsilon) = 1 + i\epsilon G + \mathcal{O}(\epsilon^2) + \dots$$

- The operator G is called a “generator” of the group
- The unitarity of U requires G to be Hermitian
 - $G = G^\dagger$
- The infinitesimal transformation is an element of the group
 - $[H, G] = 0$
- Noether’s theorem in quantum mechanics:
 - The observable corresponding to G is conserved

GLOBAL GAUGE SYMMETRY:

- From Electromagnetism, we have "gauge" transformations:

- Maxwell's laws are invariant under:

$$\phi = A_0 \rightarrow A_0 - \dot{\chi} \quad \mathbf{A} \rightarrow \mathbf{A} + \nabla\chi \quad A_\mu \rightarrow A_\mu - \partial_\mu\chi$$

- Consider the Dirac equation $(i\cancel{D} - m)\psi = 0$

- if we rotate the phase of ψ through all of space-time

$$\psi \rightarrow e^{i\theta}\psi$$

- the Dirac equation remains valid (just an overall phase)

- (n.b. May be easier to see if we consider the Lagrangian

$$\mathcal{L} = i\hbar \bar{\psi}\gamma^\mu\partial_\mu\psi - mc \bar{\psi}\psi \quad \begin{array}{l} \psi \rightarrow e^{i\theta}\psi \\ \bar{\psi} \rightarrow e^{-i\theta}\bar{\psi} \end{array}$$

LOCAL GAUGE TRANSFORMATION

- Now consider a more radical transformation:
 - Adjust the phase of the field as a function of space time
 - i.e. θ becomes a function of x

$$\theta \rightarrow \theta(x) \quad e^{-i\theta} \Rightarrow e^{-i\theta(x)}$$

- this is called a "local gauge transformation"
- now consider the Dirac equation
 - $\partial_\mu \psi \Rightarrow \partial_\mu (e^{i\theta(x)} \psi) = e^{i\theta} (\partial_\mu \psi) + i(\partial_\mu \theta) e^{i\theta} \psi$
 - $(i\cancel{\partial} - m)\psi = 0 \Rightarrow e^{i\theta} \times [i\cancel{\partial} - (\cancel{\partial}\theta) - m] \psi = 0$
- extra term in the equation!

LOCAL GAUGE SYMMETRY

- Promote local gauge transformations to a symmetry
 - *we require* the equation to be invariant under local gauge transformations (i.e. space-time dependent phase rotations)

- The symmetry/invariance can be restored if:

- we add a term to the equation

$$(i\partial - m)\psi = 0 \Rightarrow (i\partial - qA - m)\psi = 0$$

- where:

$$A_\mu \rightarrow A_\mu - \frac{1}{q}\partial_\mu\theta(x) \quad \psi \rightarrow e^{i\theta(x)}\psi$$

$$(i\partial - qA - m)\psi = 0$$

$$\Rightarrow e^{i\theta(x)} \times [i\partial - (\partial\theta) - qA + \partial\theta - m] \psi = 0$$

WHAT HAPPENED:

- We required the Dirac equation to be invariant under local gauge transformation
- this introduced a new field A with its own transformation
- Note:
 - A is a “vector” particle: i.e. A_μ
 - its transformation is the same as the EM gauge transformation
 - it couples to the Dirac field with a strength controlled by q
 - (it must be massless to preserve the symmetry)
- It has all the properties of a photon interacting with a Dirac particle with charge q
- electromagnetism is a “U(1) local gauge theory”

LINGO:

- "gauge symmetry" = "gauge invariance":
 - generalization of "phase symmetry"
- "covariant derivative":
$$\partial_\mu \rightarrow \partial_\mu + iqA_\mu$$
- "gauge boson"
 - vector field introduced for local gauge invariance
- "gauge theory"
 - particle system that has a gauge symmetry

GENERALIZATION:

- Consider the group SU(2)
 - "2x2 unitary matrices with determinant 1"
 - we can parameterize the group as follows:

$$U = U(\vec{\theta}) = e^{i\frac{g}{2}\vec{\theta}\cdot\vec{\sigma}}$$

- where σ are Pauli matrices
- Note:
 - we can consider σ as generators of the group
 - there are three parameters which parametrize the group
 - the matrices act on two-component vectors/spinors

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

"NON-ABELIAN GAUGE SYMMETRY"

- Now consider a theory in which we postulate:
 - "local gauge invariance under SU(2)"
 - θ parameters become space-time dependent

$$\vec{\theta} \rightarrow \vec{\theta}(x)$$

- the "space/objects" we act on have two component

$$\psi \equiv \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \rightarrow e^{i\frac{g}{2}\vec{\theta}\cdot\vec{\sigma}} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}$$

- for Dirac particles, this means that we are considering a pair of Dirac fields (each with 4 components) that transform under SU(2) operators

GAUGE INVARIANCE

- Like before, gauge invariance requires new fields because of the space-time dependence of $\theta(x)$

- so we introduce three fields (A_i) that transform as follows:

$$\vec{A}_\mu \rightarrow \vec{A}_\mu - \frac{1}{2} \partial_\mu \theta - \frac{g}{2} \epsilon_{ijk} \theta_i A_\mu^j$$

- one can show that this preserves the invariance under the SU(2) transformations for this equation of motion

$$(i\not{\partial} - \frac{g}{2} \vec{\sigma} \cdot \vec{A} - m)\psi = 0$$

- the extra term in the A transformation results from the fact that the the σ matrices do not commute.

WHAT HAPPENED:

- We now have a system of two fermions, each described by the Dirac equation
- local gauge symmetry requires three fields to cancel the “leftover” terms from the transformation
 - we have three new gauge fields which mediate interactions
- the additional term
$$\frac{g}{2} \vec{\sigma} \cdot \vec{A} \psi$$
- leads to interactions between the gauge bosons themselves
 - i.e. the bosons are “charged”

$$\frac{g}{2} \vec{\theta} \times \vec{A}_\mu$$

FOUNDATIONS:

- Quantum field theory arises from
 - special relativity
 - quantum mechanics
- with Local Gauge Invariance
 - we introduce interactions via bosons required to maintain the symmetry
 - however, the bosons must be massless
- Note the difference between:
 - the symmetry group (i.e. possible operations)
 - the objects on which they act
 - imposing symmetries on their behaviour (equations of motion, Lagrangian, etc.)

NEXT TIME

- Please read 10.5, 10.6
 - You can skip 10.5.1 unless it helps you understand 10.5.2
 - Problem Set 2 due on Tuesday